



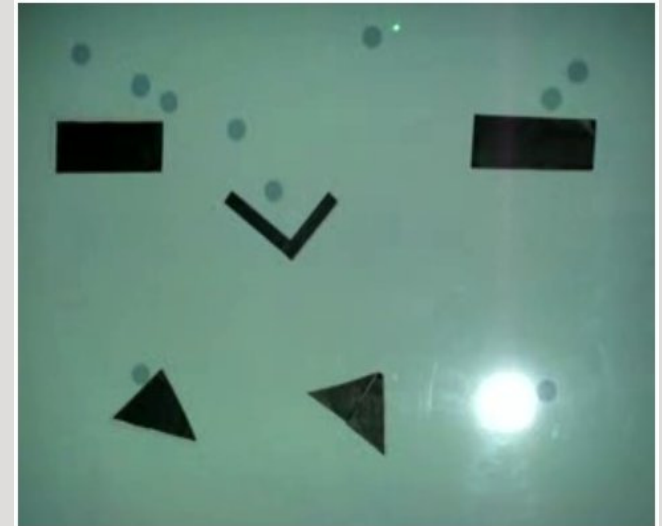
# **Shale:** **SHAdows LEvers & Wheels**

Paul Gerhardt  
Amanda Orin  
Tomas Ramirez  
Jessa Rothenberg  
Kaiti Trimble



# Presentation Overview

- Sponsor & Background
- Problem
- Solution
  - Conceptual Overview
- Requirements
  - Functional Requirements
    - User Interfaces
  - Environmental Requirements
- Architecture Overview
- Software Demo
- Summary of Points





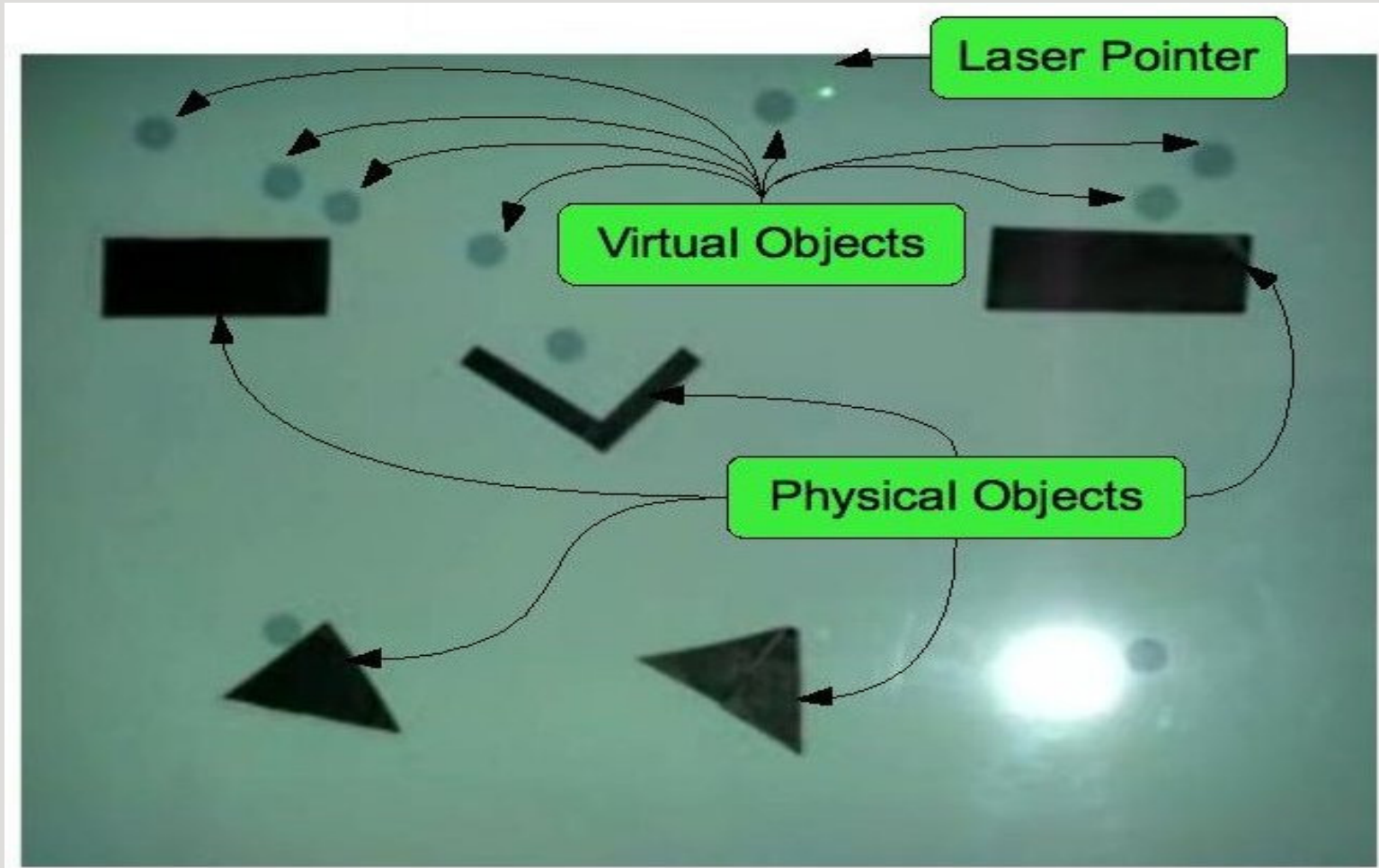
## Sponsor & Background

- Sponsored by Craft Technology Lab
  - Subsidiary of the L3D
  - Craft objects with embedded intelligence
- Derived from LaserBall Project
  - Joins physical & virtual objects
  - Non-mechanical interaction
  - Limited performance





# LaserBall





## Problem

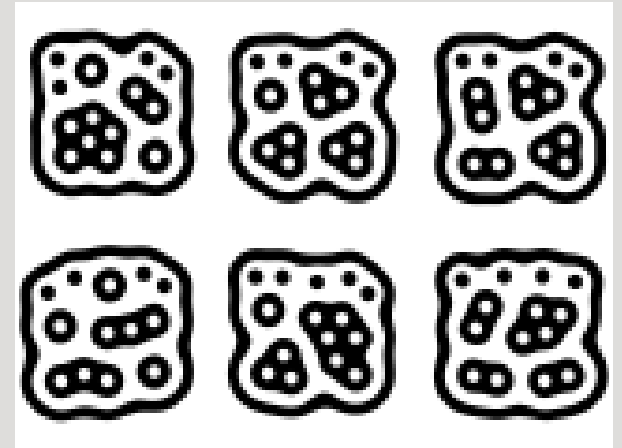
- Interactions between virtual and physical objects, controlled to some degree by a user.
  - Expand LaserBall idea
  - Incorporate reactive physical objects
  - Wireless communication





# Presentation Overview

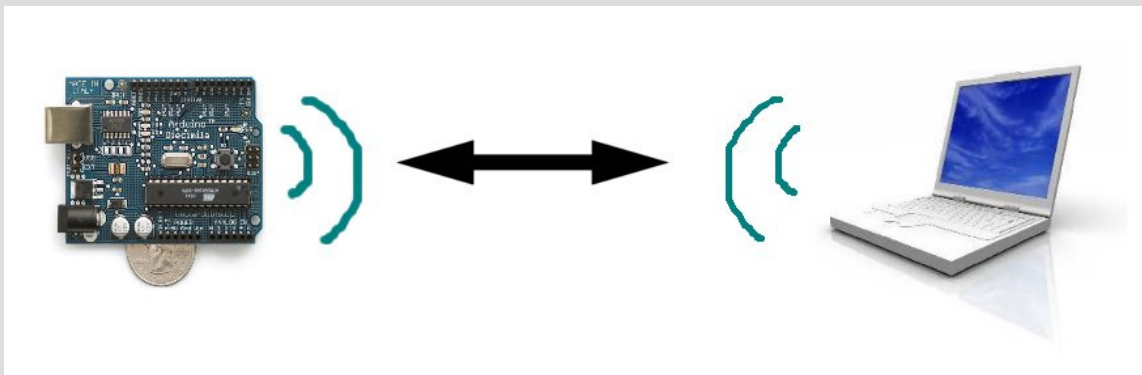
- Sponsor & Background
- Problem
- ***Solution***
  - Conceptual Overview
- Requirements
  - Functional Requirements
    - User Interfaces
  - Environmental Requirements
- Architecture Overview
- Software Demo
- Summary of Points





## Solution – Project Shale

- Extend the LaserBall project with reactive physical components
  - See saw, Bumper, Sound Emitter
- Wireless communication with components
  - Xbee (Zigbee 802.15.4 mesh networking)

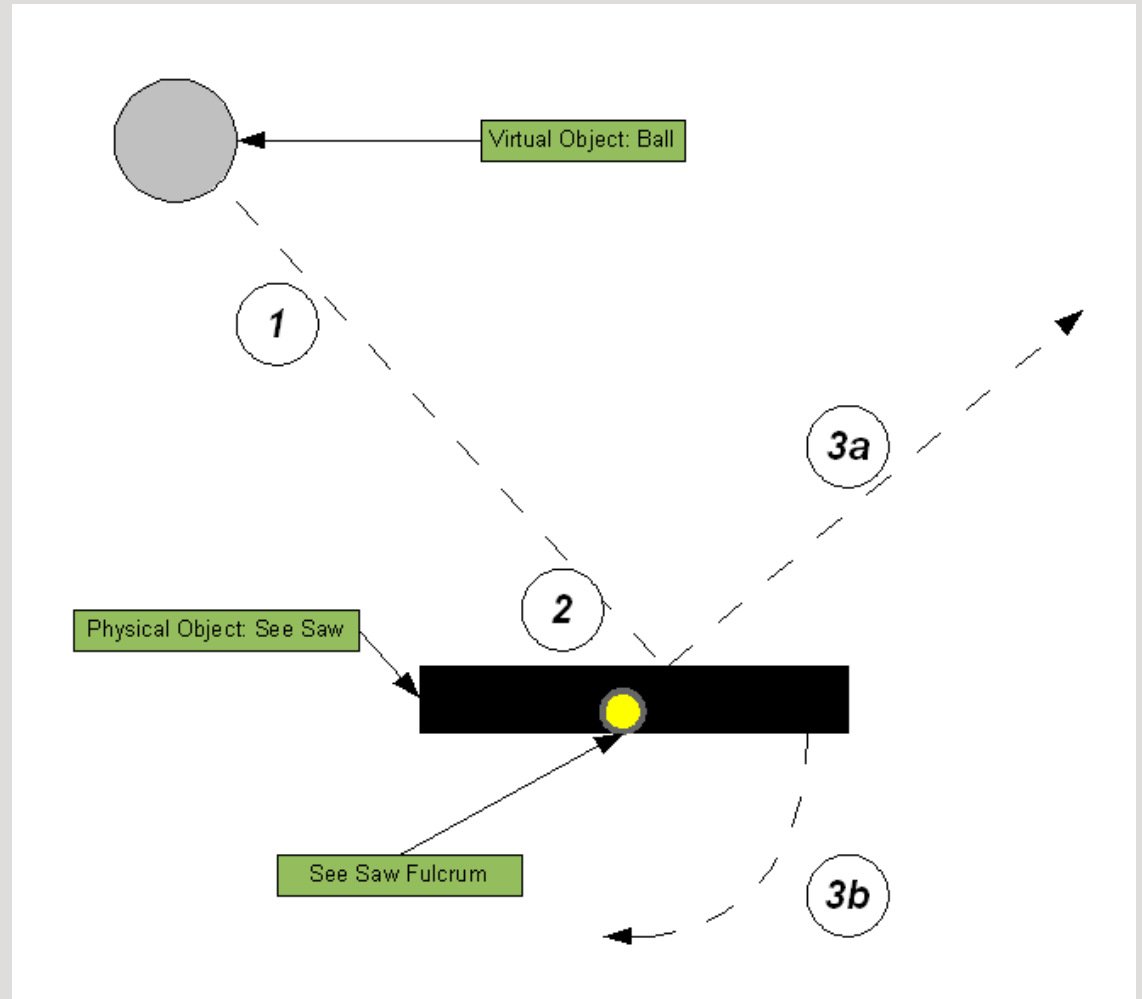




# Project Shale: An Example

## Steps:

1. Virtual Object (the ball) moves towards the Physical Object (the see saw)
2. Virtual Object and Physical Object collide
3. A) Virtual Object (ball) ricochets off in a different direction  
B) Physical Object (see saw) turns in reaction to the collision

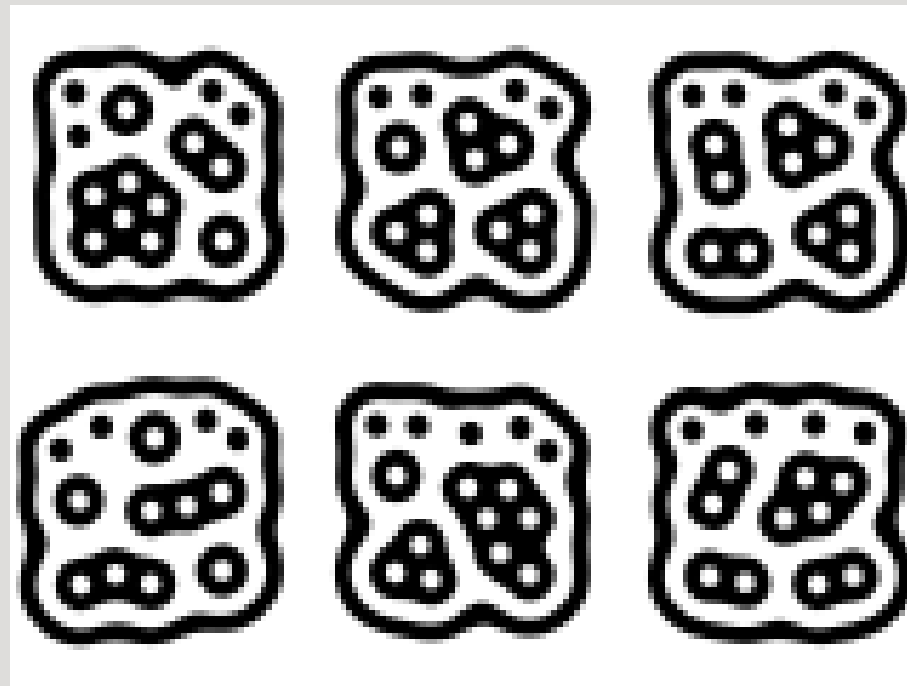






## Solution – Project Shale

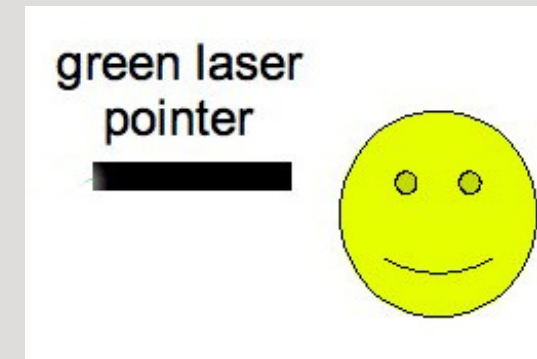
- Recognize Physical Objects
  - LED fiducial markers



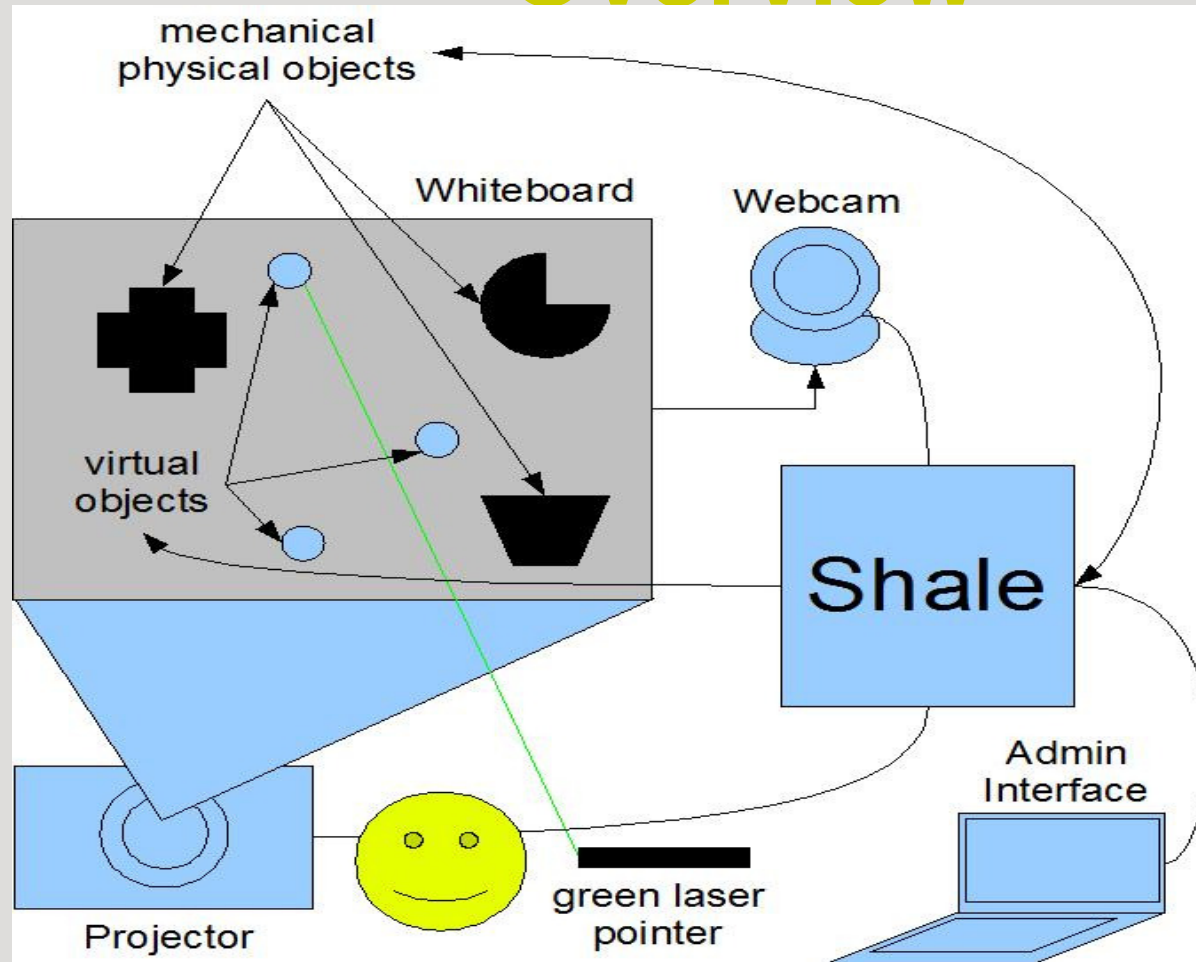


# Presentation Overview

- Sponsor & Background
- Problem
- Solution
  - **Conceptual Overview**
- **Requirements**
  - **Functional Requirements**
    - User Interfaces
  - Environmental Requirements
- Architecture Overview
- Software Demo
- Summary of Points



# Conceptual Overview





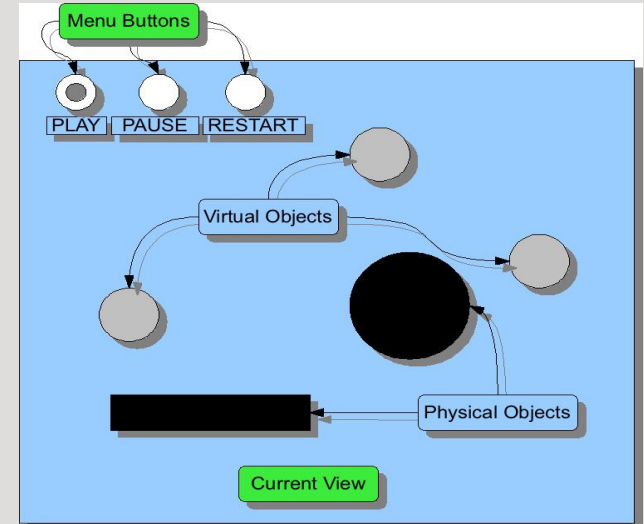
# Functional Requirements

- Demonstrate interactions between physical and virtual objects
  - Project virtual objects
  - Detect and control physical objects
  - Respond to user actions
- Additional requirements
  - Debugging interface
  - GUI



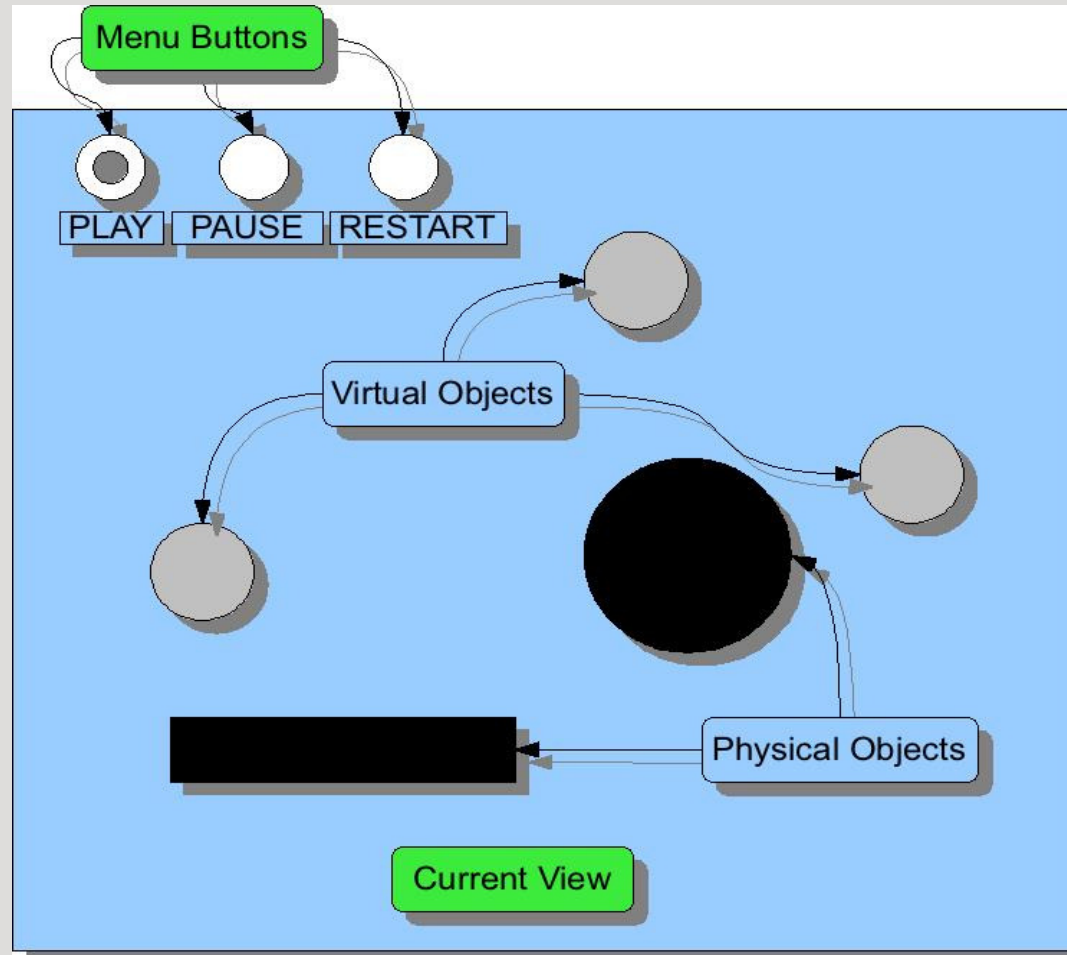
# Presentation Overview

- Sponsor & Background
- Problem
- Solution
  - Conceptual Overview
- Requirements
  - Functional Requirements
    - ***User Interfaces***
    - ***Environmental Requirements***
- Architecture Overview
- Software Demo
- Summary of Points



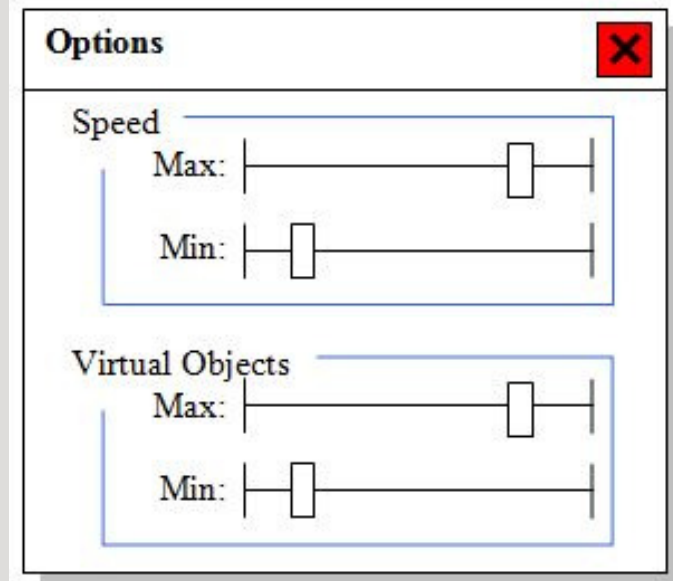
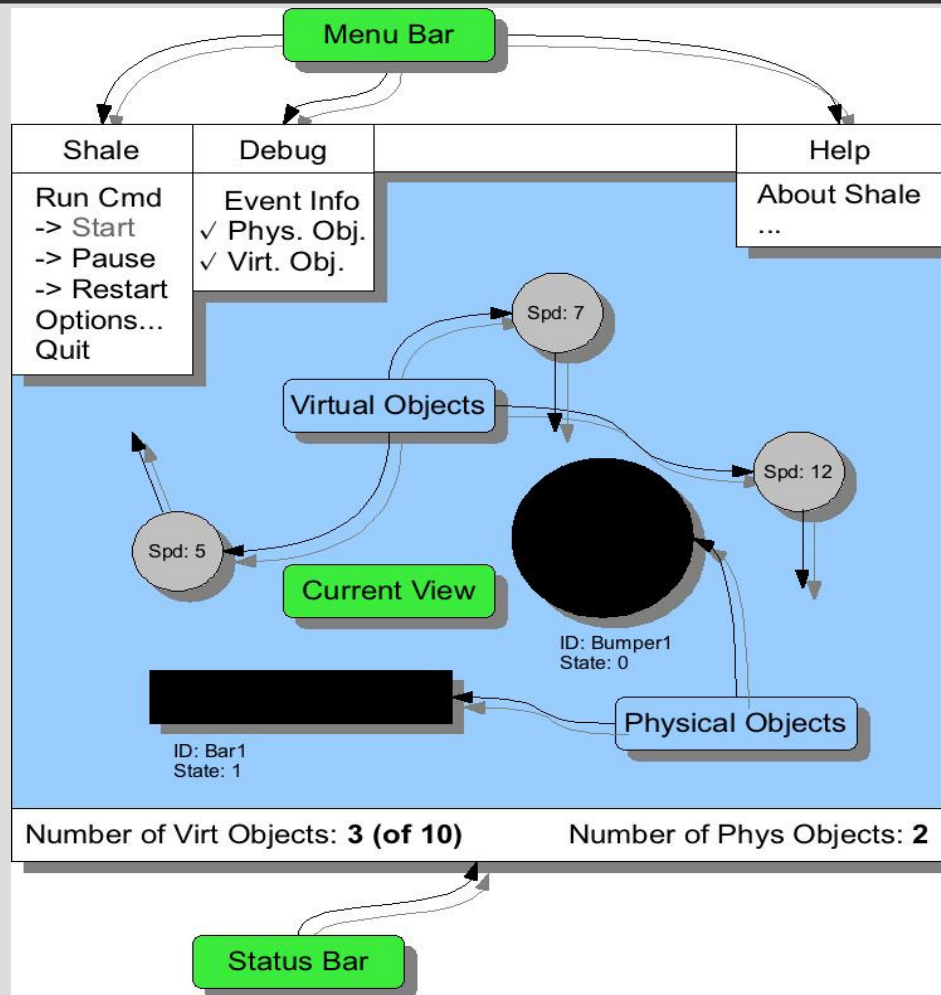


# Standard User Interface





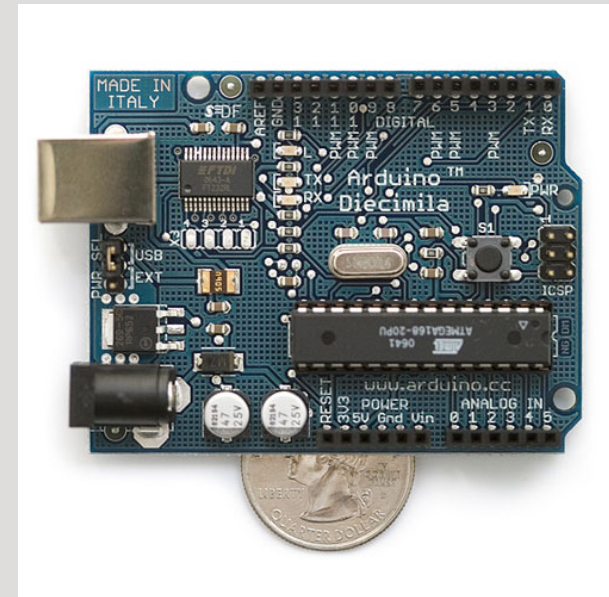
# Administrative Interface





# Environmental Requirements

- Development Environment
  - Processing PDE 0135 (Cross-platform)
  - JMyron Image Processing Library
- Hardware
  - Projector
  - Web camera
  - Projection Surface
  - Laser Pointer
  - Arduino microcontrollers

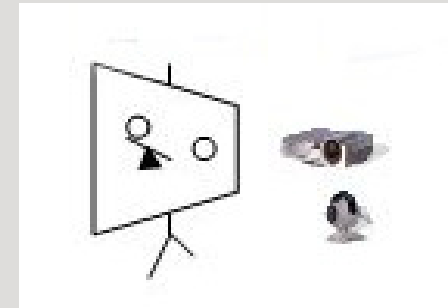






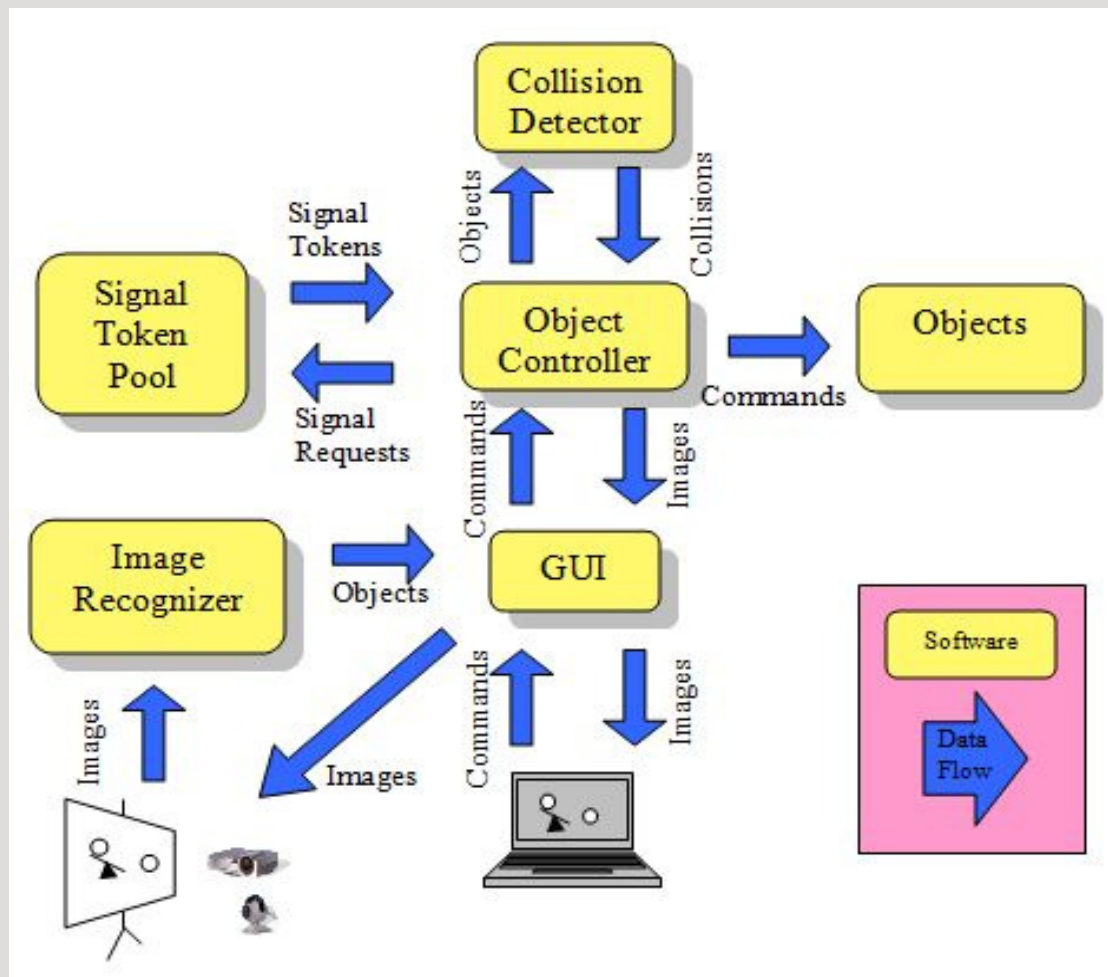
# Presentation Overview

- Sponsor & Background
- Problem
- Solution
  - Conceptual Overview
- Requirements
  - Functional Requirements
    - User Interfaces
  - Environmental Requirements
- **Architecture Overview**
- **Software Demo**
- Summary of Points



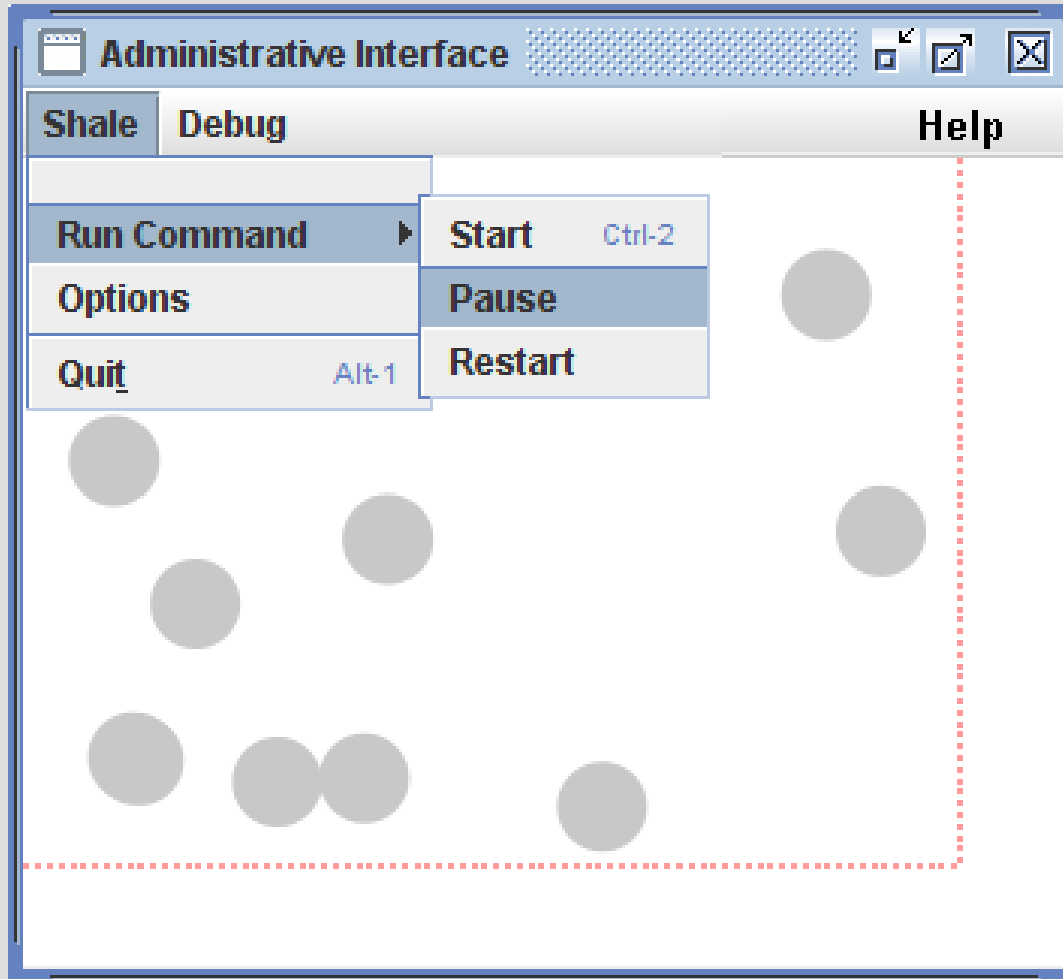


# Shale Architecture





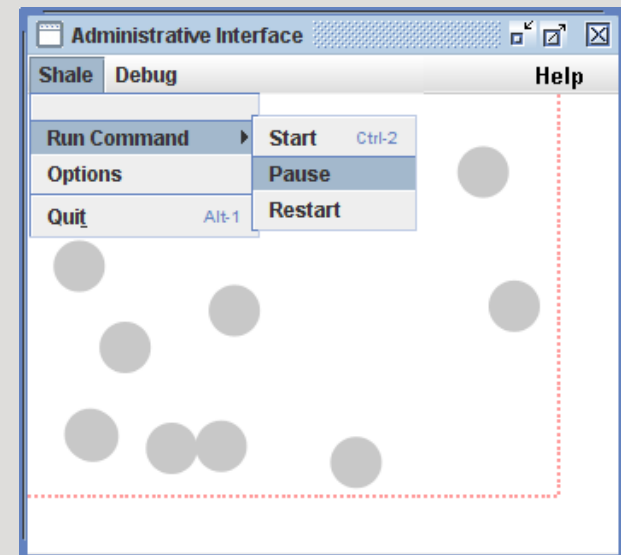
# Demonstration





# Summary of Points

- Sponsor & Background
- Problem
- Solution
  - Conceptual Overview
- Requirements
  - Functional Requirements
    - User Interfaces
  - Environmental Requirements
- Architecture Overview
- Software Demo
- Summary of Points





# ***QUESTIONS?***